

# Rule Induction Association Rules

### Unsupervised Learning

- ▶ No goal class (either Y nor G).
- We have N observations of X: (x<sub>1</sub>,...,x<sub>N</sub>), x<sub>i</sub> ∈ {0,1}<sup>p</sup> (some dimensions may be numeric).
- We aim to reason about P(X).
- ▶ For *p* < 4 effective nonparametric methods exist.
- ► For *p* high **Curse of dimensionality** appears.
- We estimate rough global models
  - mixtures of gaussians (clustering)
  - simple statistics characterizing P(X).

#### Curse of Dimensionality

Unit ball in p dimensions centered in the origin. Distance from the origin to closest neighbor is roughly:

$$d(p,N) = \left(1 - \frac{1}{2}^{\frac{1}{N}}\right)^{\frac{1}{p}}$$





FIGURE 2.6. The curse of dimensionality is well illustrated by a subcubical neighborhood for uniform data in a unit cube. The figure on the right shows the side-length of the subcube needed to capture a fraction r of the volume of the data, for different dimensions p. In ten dimensions we need to cover 80% of the range of each coordinate to capture 10% of the data.

### High p – Nearest Neighbor Approximation May Fail



FIGURE 2.8. A simulation example with the same setup as in Figure 8.7. Here the function is constant in all but one dimension:  $F(X) = \frac{1}{2}(X_1 + 1)^3$ . The variance dominates.

# Places with high P(X)

- We search places with high appearance of data samples
- using various languages
  - association rules
    - conjunctive rules
    - really many dimensions p and (usually) binary data
  - clustering (last week)
    - means of clusters, list of gaussians
    - usually continuous features.

#### Association Rules

- Usually binary data  $X_{ij} \in \{0,1\}^{N \times p}$
- ▶ Value = 1 is our interest; for example purchase.
- p may be very large; for example the size of sortiment of an market.
- Popular application: Market basket analysis.
- Generally: We look for L prototypes v<sub>1</sub>,..., v<sub>L</sub> ∈ X<sup>p</sup> such that P(v<sub>ℓ</sub>) is relatively large.
- 'Bump hunting' may be used (gradient search).
- With large p, we do not have enough data to estimate P(vℓ) since number of observations with P(X = vℓ) is too small.
- ▶ We seek for regions where P(x) is large, that can be written as conjunctive rule on dimension conditions  $\bigcap_{j=1}^{p} (X_j \in s_j)$  where  $s_j$  are selected values of the feature  $X_j$ .

# Hypothesis space for Apriori



ESL book Figure:

**FIGURE 14.1.** Simplifications for association rules. Here there are two inputs  $X_1$  and  $X_2$ , taking four and six distinct values, respectively. The red squares indicate areas of high density. To simplify the computations, we assume that the derived subset corresponds to either a single value of an input or all values. With this assumption we could find either the middle or right pattern, but not the left one.

#### Market Basket Analysis

- ▶ For very large datasets,  $p \approx 10^4$ ,  $N \approx 10^8$ ; in unit ball is the distance to the nearest neighbour  $\approx 0.9981$ .
- Simplifications: Test on feature X<sub>j</sub> either equal to a specific value or no restriction at all,
- I select combinations of items with higher number of occurences (support) than predefined threshold t.
- ► I select <u>all</u> combinations fulfilling conditions above.
- Categorical variables may be codded by dummy variables in advance (if not too many).

# Apriori Algorithm

- 1. Create list of candidates, one-element subsets of the feature space, for example: {*bread*} meaning  $X_{bread} = 1$ .
- 2. For each candidate count support in data.
- 3. Discard candidates with support less than t (predefined threshold).
- 4. For each length  $i = 2, \ldots$ 
  - 4.1 Generate list of candidates of the length *i*.
    Join any two candidates from previous step having *i* 2 elements common. (*More prunning possible.*)
  - 4.2 For each candidate, count support in data.
  - 4.3 Discard candidates with support < t.
- 5. Until empty list of candidates.

## Properties of the Apriori Algorithm

- ▶ Applicable for very large data (with high treshold *t*).
- ► The key idea:
  - Only few of  $2^{K}$  combinations have high support > t,
  - ► subset of high-support combination has also high support.
- The number of passes through the data is equal to the size of the longest supported combination. The data does not to be in memory simultaneously.

#### Association Rules !

- From each supported itemset  $\mathcal{K}$  found by Apriori algorithm we create a list of **association rules**, implications of the form  $A \Rightarrow B$  where:
  - A, B are disjoint and  $A \cup B = \mathcal{K}$
  - A is called antecedent
  - ► *B* is called succedent (consequent).
- Support of the rule T(A ⇒ B) is defined as support of the itemset K, that is support of the conjunction A&B.

### Precision, Lift of a Rule !

There are two important measures for a rule  $A \Rightarrow B$ :

Confidence (predictability, přesnost)

$$C(A \Rightarrow B) = \frac{T(A \Rightarrow B)}{T(A)}$$

that is an estimate of P(B|A),

- Expected precision T(B) is an estimate of P(B),
- Lift is the ration of confidence and expected precision:

$$L(A \Rightarrow B) = \frac{C(A \Rightarrow B)}{T(B)}$$

that is an estimate of  $\frac{P(A\&B)}{P(A) \cdot P(B)}$ .

#### Association Rule Example

ESL book example:

Association rule 2: Support 13.4%, confidence 80.8%, and lift 2.13.

language in home = Englishhouseholder status = ownoccupation = {professional/managerial}  $\downarrow$ income > \$40,000

- $\mathcal{K} = \{ \text{English, own, pref/man, income} > \$40000 \},\$
- ▶ 13.4% people has all four properties,
- ▶ 80.8% of people with {English, own, pref/man} have income> \$40000,
- T(income > \$40000) = 37.94%, therefore Lift = 2.13.

# The Goal of Apriori Algorithm !

- Apriori finds <u>all</u> rules with high support.
- Frequently, it finds thousends of rules.
- ▶ We usually select lower treshold *c* on confidence, that is we select rules with  $T(A \Rightarrow B) > t$  and  $C(A \Rightarrow B) > c$ .
- Conversion of itemsets to rules is usually relatively fast compared to seach of itemsets.
- See lispMiner for user interface and a lot of more.

# Demographical Data ESL Example

Feature	Demographic	# Values	Type
1	Sex	2	Categorical
2	Marital status	5	Categorical
3	Age	7	Ordinal
4	Education	6	Ordinal
5	Occupation	9	Categorical
6	Income	9	Ordinal
7	Years in Bay Area	5	Ordinal
8	Dual incomes	3	Categorical
9	Number in household	9	Ordinal
10	Number of children	9	Ordinal
11	Householder status	3	Categorical
12	Type of home	5	Categorical
13	Ethnic classification	8	Categorical
14	Language in home	3	Categorical

### Demographical Example – Continuing

- N = 9409 questionmarks, the ESL authors selected 14 questions.
- Preprocessing:
  - > na.omit() remove records with missing values,
  - ordinal features cut by median to binary,
  - for categorical create dummy variable for each category.
- Apriori input was matrix 6876 × 50.
- Output: 6288 association rules
  - with max. 5 elements
  - with support at least 10%.

#### Negated Literals – Useful, Problematic

Association rule 3: Support 26.5%, confidence 82.8% and lift 2.15.

 $\begin{bmatrix} \text{language in home} &= English \\ \text{income} &< \$40,000 \\ \text{marital status} &= not married \\ \text{number of children} &= 0 \\ & \downarrow \end{bmatrix}$ 

education  $\notin \{ college \ graduate, \ graduate \ study \}$ 

# Non-frequent Values Dissapear



#### Relative Frequency in Association Rules



#### Relative Frequency in Data

# Unsupervised Learning as Supervised Learning



- We add additional attribute  $Y_G$ .
- $Y_G = 1$  for all our data.
- ▶ We generate randomly a dataset of simillar size with uniform distribution, set Y<sub>G</sub> = 0 for this artificial data.
- The task is to separate  $Y_G = 1$  and  $Y_G = 0$ .

#### Generalize Association Rules

- ► We search for high lift, where probability of conjunction is greater than expected.
- Hypothesis is specified by column indexes j and subsets of values s<sub>j</sub> corresponding features X<sub>j</sub>. We aim:

$$\hat{P}\left(igcap_{j\in\mathcal{J}}(X_j\in s_j)
ight)>>rac{1}{N}\sum_1^NI\left(igcap_{j\in\mathcal{J}}(x_{ij}\in s_j)
ight)$$

- On the data from previous slide, CART (decision tree alg.) or PRIM ('bump hunting') may be used.
- Figure on previous slide: Logistic regression on tensor product of natural splines.
- Other methods may be used. All are heuristics compared to full evaluation by Apriori.

# PRIM = Bump Hunting Patient Rule Induction Method

- ► We search iteratively areas with high Y; for each area we create a rule
- CART after approximately log<sub>2</sub>(N) 1 steps looses all data, PRIM can afford approximately log(N)/log(1-α) steps.
   For N = 128 and α = 0.1 it is 6 and 46 resp. 29, since data counts must be whole numbers.

### PRIM Patient Rule Induction Method !

- $1.\,$  Take all data and full feature space,  $\alpha=$  0.05 or 0.10
- 2. Find  $X_j$  and its upper or lower boundary such that the removal of  $\alpha \cdot 100\%$  observations gives maximum increase of the overall mean of the remaining area.
- 3. Repeat 2. until at least 10 observations remain.
- 4. Extend the area in any direction if it increases the mean.
- 5. From the above list of areas, select the one (# of observations) best by crossvalidation. We call this area  $B_1$ .
- 6. Remove data in  $B_1$  from the dataset and continue 2 to 5, create  $B_2$ , ..., until a stop criterion.



















n.





# R Code Example

```
library("arules")
data("AdultUCI")
#48842 rows (elements/itemsets/transactions) and
# 115 columns (items) and a density of 0.1089939
itemFrequencyPlot(Adult, support = 0.1, cex.names=0.8)
rules <- apriori(Adult, parameter = list(support = 0.01,
confidence = 0.6))
#set of 276443 rules
rulesIncomeSmall <- subset(rules, subset = rhs %in%
"income=small"& lift > 1.2)
inspect(head(rulesIncomeSmall, n = 1, by = "confidence"))
#lhs rhs support confidence lift
# 1 marital-status=Married-civ-spouse,
# capital-gain=High,
```

# native-country=United-States => income=large 0.01562180 0.6849192 4.266398



### MARS Multivariate Adaptive Regression Splines

- generalization of linear regression and decision trees CART
- for each feature and each data point we create a mirror pair of basis functions
- $(x t)_+$  and  $(t x)_+$  where + denotes non-negative part, minimum is zero.
- we have the set of functions

$$\mathcal{C} = \{(X_j - t)_+, (t - X_j)_+\}_{t \in \{x_{1,j}, x_{2,j}, \dots, x_{N,j}\}, j=1,2,\dots,p}$$

▶ that is 2*Np* functions for non–duplicated data points.

### **MARS** – continuation

our model is in the form

$$f(X) = \beta_0 + \sum_{m=1}^M \beta_m h_m(X)$$

where  $h_m(X)$  is a function from C or a product of any amount of functions from C

- for a fixed set of h<sub>m</sub>'s we calculate coefficients β<sub>m</sub> by usual linear regression (minimizing RSS)
- ▶ the set of functions *h<sub>m</sub>* is selected itterativelly

#### MARS - basis selections

- ▶ We start with  $h_0 = 1$ , we put this function into the model  $\mathcal{M} = \{h_0\}.$
- $\blacktriangleright$  We consider the product of any member  ${\mathcal M}$  with any pair from  ${\mathcal C}$

 $\hat{eta}_{M+1}h_\ell(X)\cdot(X_j-t)_++\hat{eta}_{M+2}h_\ell(X)\cdot(t-X_j)_+,h_\ell\in\mathcal{M}$ 

we select the one minimizing training error RSS (for any product candidate, we estimate  $\hat{\beta}).$ 

- $\blacktriangleright$  Repeat until predefined number of functions in  ${\cal M}$
- The model is usually overfitted. We select (remove) iteratively the one minimizing the increase of training RSS. We have a sequence of models f<sub>λ</sub> for different numbers of parameters λ.
- (we want to speed-up crossvalidation for computational reasons)
- ▶ we select \(\lambda\) (and the model) minimizing generalized crossvalidation

$$GCV(\lambda) = \frac{\sum_{i=1}^{N} (y_i - \hat{f}_{\lambda}(x_i))^2}{(1 - M(\lambda)/N)^2}.$$

• where  $M(\lambda)$  is the number of effective parameters, the number of function  $h_m$  (denoted r) plus the number of knots K, the authors suggest to multiply K by 3:  $M(\lambda) = r + 3K$ .

#### Decision trees from MARS

- ► The MARS is related with standard decision tree algorithm.
- We replace piecewise linear functions with piecewise constant functions *I*(*x* − *t* > 0) and *I*(*x* − *t* ≤ 0)
- ► If a function h<sub>m</sub> is used in a product we remove it from the model. Therefore, it is used maximally once: we get binary structure of the tree.
- ▶ and we have the standard decision tree algorithm (ID3, CART).